HART® field temperature transmitter Models TIF50, TIF52

WIKA data sheet TE 62.01













for further approvals see page 10



Applications

- Plant construction
- Process engineering
- General industrial applications
- Oil and gas

Special features

- Setting of units and measuring range possible on site (only model TIF52)
- Different hazardous area approvals
- The following settings are possible via external software:
 - Dual sensor, redundant measurement possible
 - Customer-specific characteristic curves programmable



Field temperature transmitters models TIF50, TIF52

Description

The TIF series field temperature transmitters, consisting of a rugged field case, model T32 temperature transmitter and a model DIH display, have been designed for general use in process engineering.

They offer high accuracy, galvanic isolation and excellent protection against electromagnetic influences (EMI). Via HART® protocol, the TIFxx is configurable (interoperable) with a variety of open configuration tools.

In addition to the different sensor types, e.g. sensors in accordance with DIN EN 60751, JIS C1606, DIN 43760, IEC 60584 or DIN 43710, customer-specific sensor characteristics can also be defined, through the input of value pairs (user-defined linearisation). Through the configuration of a sensor with redundancy (dual sensor), on a sensor failure it will automatically change over to the working sensor.

Furthermore, there is the possibility to activate sensor drift detection. With this, an error signalling occurs when the magnitude of the temperature difference between sensor 1 and sensor 2 exceeds a user-selectable value.

The field temperature transmitter also has additional sophisticated supervisory functionality such as monitoring of the sensor lead resistance and sensor-break detection in accordance with NAMUR NE89 as well as monitoring of the measuring range. Moreover, these transmitters have comprehensive cyclic self-monitoring functionality.

Via the display it is possible to show range alarms as well as MIN and MAX values.

The field temperature transmitter is available in various field case variants. Stainless steel and aluminium can be specified.

It can be mounted directly on a wall. A pipe mounting kit is also available for fitting to pipes with a diameter of 1 ... 2".

The field temperature transmitters are delivered with a basic configuration or configured according to customer specifications.



Specifications

Field tem	Field temperature transmitter input						
Sensor type		Max. configurable measuring range	Standard	α values	Minimum measuring span ¹⁴⁾	Typical measuring deviation ²⁾	Temperature coefficient per °C typical ³⁾
Resistance	Pt100	-200 +850 °C	IEC 60751:2008	$\alpha = 0.00385$	10 K or 3.8 Ω	≤ ±0.12 °C ⁵⁾	\leq ±0.0094 °C ^{6) 7)}
sensor	Pt(x) 4) 10 1000	-200 +850 °C	IEC 60751:2008	$\alpha = 0.00385$	(greater value applies)	\leq ±0.12 °C ⁵⁾	$\leq \pm 0.0094$ °C ^{6) 7)}
	JPt100	-200 +500 °C	JIS C1606: 1989	$\alpha = 0.003916$		$\leq \pm 0.12 {}^{\circ}\text{C}^{5)}$	$\leq \pm 0.0094 {}^{\circ}\text{C} {}^{6)} {}^{7)}$
	Ni100	-60 +250 °C	DIN 43760: 1987	$\alpha = 0.00618$		$\leq \pm 0.12 {}^{\circ}\text{C}^{5)}$	$\leq \pm 0.0094~^{\circ}C^{~6)~7)}$
	Resistance sensor	$0 \dots 8,370 \Omega$			4Ω	$\leq \pm 1.68\Omega^{8)}$	$\leq \pm 0.1584~\Omega^{(8)}$
	Potentiometer 9)	0 100 %			10 %	$\leq 0.50 \% ^{10)}$	$\leq \pm 0.0100 \% ^{10)}$
Measuring of measurement	urrent during nt	Max. 0.3 mA (Pt100)					
Connection methods		1 sensor 2-/4-/3-wire or 2 sensors 2-wire (for further information, please refer to "Designation of connection terminals")					
Max. lead re	sistance	50 Ω each wire, 3-/4-wire					
Thermo-	Type J (Fe-CuNi)	-210 +1,200 °C	IEC 60584-1: 1995	5	50 K or 2 mV	≤ ±0.91 °C ¹¹⁾	$\leq \pm 0.0217 ^{\circ}\text{C}^{7)} ^{11)}$
couple	Type K (NiCr-Ni)	-270 +1,300 °C	IEC 60584-1: 1995		(greater value applies)	≤ ±0.98 °C ¹¹⁾	$\leq \pm 0.0238$ °C ^{7) 11)}
	Type L (Fe-CuNi)	-200 +900 °C	DIN 43760: 1987			≤ ±0.91 °C ¹¹⁾	$\leq \pm 0.0203 ^{\circ}\text{C}^{7)} ^{11)}$
	Type E (NiCr-Cu)	-270 +1,000 °C	IEC 60584-1: 1998	5		\leq ±0.91 °C ¹¹⁾	$\leq \pm 0.0224 ^{\circ}\text{C}^{ 7) 11)}$
	Type N (NiCrSi-NiSi)	-270 +1,300 °C	IEC 60584-1: 1995	5		\leq ±1.02 °C ¹¹⁾	$\leq \pm 0.0238 ^{\circ}\text{C}^{7)11)}$
	Type T (Cu-CuNi)	-270 +400 °C	IEC 60584-1: 1995	5		\leq ±0.92 °C ¹¹⁾	$\leq \pm 0.0191$ °C ^{7) 11)}
	Type U (Cu-CuNi)	-200 +600 °C	DIN 43710: 1985			\leq ±0.92 °C ¹¹⁾	$\leq \pm 0.0191$ °C ^{7) 11)}
	Type R (PtRh-Pt)	-50 +1,768 °C	IEC 60584-1: 1998	5	150 K	≤ ±1.66 °C ¹¹⁾	$\leq \pm 0.0338$ °C ^{7) 11)}
	Type S (PtRh-Pt)	-50 +1,768 °C	IEC 60584-1: 1995	5	150 K	≤ ±1.66 °C ¹¹⁾	$\leq \pm 0.0338$ °C ^{7) 11)}
	Type B (PtRh-Pt)	0 +1,820 °C ¹⁵⁾	IEC 60584-1: 1998	5	200 K	$\leq \pm 1.73 ^{\circ}\text{C}^{11)}$	$\leq \pm 0.0500$ °C ^{7) 12)}
	mV sensor	-500 +1,800 mV			4 mV	$\leq \pm 0.33~mV^{13)}$	$\leq \pm 0.0311 \ mV^{7) \ 13)$
Connection methods		1 sensor or 2 sensors (for further information, please refer to "Designation of connection terminals")					
Max. lead resistance		$5 k\Omega$ each wire					
Cold junction compensation, configurable		internal compensation or external with Pt100, with thermostat or off					

- 1) Other units e.g. °F and K possible
- 2) Measuring deviations (input + output) at ambient temperature 23 °C \pm 3 K, without influence of lead resistances; for example calculations see page 5
- 3) Temperature coefficients (input + output) per °C
- 4) x configurable between 10 ... 1,000
- 5) Based on 3-wire Pt100, Ni100, 150 °C MV
- 6) Based on 150 °C MV
- 7) In the ambient temperature range -40 \dots +85 $^{\circ}\text{C}$
- 8) Based on a sensor with max. 5 $k\Omega$
- 9) Rtotal: 10 ... 100 kΩ
- 10) Based on a potentiometer value of 50 %

- 11) Based on 400 °C MV with cold junction compensation error
- 12) Based on 1.000 °C MV with cold junction compensation error
- 13) Based on measuring range 0 ... 1 V, 400 mV MV
- 14) The transmitter can be configured below these limits, but this is not recommended due to loss of accuracy.
- 15) Specifications valid only for measuring range between 450 ... 1,820 $^{\circ}\text{C}$

MV = measured value (temperature measured values in $^{\circ}$ C)

Note:

The transmitter can be configured below these limits, but this is not recommended due to loss of accuracy.

The selection of the sensor is only possible via the HART® software (e.g. WIKA_T32) or the HART® communicator (e.g. FC475, MFC4150).

WIKA configuration software WIKA_T32: Free download from www.wika.com

User linearisation

Via software, customer-specific sensor characteristics can be stored in the transmitter, so that further sensor types can be used. Number of data points: Minimum 2; maximum 30

Monitoring functionality with 2 sensors connected (dual sensor)

Redundancy

In the case of a sensor error (sensor break, lead resistance too high or outside the measuring range of the sensor) of one of the two sensors, the process value will be only based on the error-free sensor. Once the error is rectified, the process value will again be based on the two sensors or on sensor 1.

Ageing control (sensor-drift monitoring)

An error signal on the output is activated if the value of the temperature difference between sensor 1 and sensor 2 is higher than a set value, which can be selected by the user. This monitoring only generates a signal if two valid sensor values can be determined and the temperature difference is higher than the selected limit value.

(Cannot be selected for the "Difference" sensor function, since the output signal already indicates the difference value).

Sensor functionality when 2 sensors have been connected (dual sensor)

Sensor 1, sensor 2 redundant

The 4 ... 20 mA output signal delivers the process value of sensor 1. If sensor 1 fails, the process value of sensor 2 is output (sensor 2 is redundant).

Mean value

The 4 ... 20 mA output signal delivers the mean value of the two values from sensor 1 and sensor 2. If one sensor fails, the process value of the error-free sensor is output.

Minimum value

The 4 ... 20 mA output signal delivers the lower of the two values from sensor 1 and sensor 2. If one sensor fails, the process value of the error-free sensor is output.

Maximum value

The 4 ... 20 mA output signal delivers the higher of the two values from sensor 1 and sensor 2. If one sensor fails, the process value of the error-free sensor is output.

Difference

The 4 ... 20 mA output signal delivers the difference between sensor 1 and sensor 2. If one sensor fails, an error signalling will be activated.

Display, operating unit	Model TIF50	Model TIF52		
Display principle	LCD, rotatable in 10° steps			
Measured value of display	7-segment LCD, 5-digit, character size 9 mm			
Bar graph	20-segment LCD			
Info line	14-segment LCD, 6-digit, character si	14-segment LCD, 6-digit, character size 5.5 mm		
Status indicators	 ★ : HART® mode (signalling of HART® parameter adoption) ∴ Unit lock ∴ Warnings or error messages 			
Indication range	-9999 99999			
Measuring rate	approx. 4/s			
Accuracy	±0.1 % of measuring span	±0.05 % of measuring span		
Temperature coefficient	±0.1 % of measuring span / 10 K			
HART® functionality				
■ Access control	-	Secondary master		
Automatically set parameters				
Available commands	-	Unit, measuring range start/end, format, zero point, span, damping, polling address		
Identified commands	Generic mode: 1, 15, 35, 44	Generic mode: 0, 1, 6, 15, 34, 35, 36, 37, 44		
■ Multidrop	Not supported	Measured values are automatically taken from the HART® digital data and displayed		

Rise time, damping, measuring rate			
Rise time t ₉₀	Approx. 0.8 s		
Damping, configurable	Off; configurable between 1 s and 60 s		
Switch-on time (time to get the first measured value)	Max. 15 s		
Measuring rate 1)	Measured value update approx. 3/s		

Bold: Basic configuration

1) Valid only for RTD/single thermocouple sensor

Analogue output, output limits, signalling, insulation resistance					
Analogue output, configurable	Linear to temperature per IEC 60751 / JIS C1606 / DIN 43760 (for resistance sensors) or linear to temperature per IEC 584 / DIN 43710 (for thermocouples) 4 20 mA or 20 4 mA, 2-wire				
Output limits, configurable per NAMUR NE43 customer-specifically adjustable	Lower limit 3.8 mA 3.6 4.0 mA	upper limit 20.5 mA 20.0 21.5 mA			
Current value for signalling, configurable per NAMUR NE43 Substitute value	Downscale < 3.6 mA (3.5 mA) 3.5 12.0 mA	upscale > 21.0 mA (21.5 mA) 12.0 23.0 mA			
In simulation mode, independent from input signal, simulation values	In simulation mode, independent from input signal, simulation value configurable from 3.5 23.0 mA				
Load R _A (without HART®)	$R_A \leq \left(U_B - 13.5 V\right) / 0.023 \; A$ with R_A in Ω and U_B in V				
Load R _A (with HART®)	$R_A \leq \left(U_B - 14.5V\right)/0.023A$ with R_A in Ω and U_B in V				
Insulation voltage (input to analogue output)	AC 1,200 V (50 Hz / 60 Hz); 1 s				
Insulation specification to DIN EN 60664-1:2003	Overvoltage category III				

Bold: Basic configuration

Explosion protection, power supply					
Model	Approvals	Permissible ambient/storage temperature (in accordance with the relevant temperature classes)	Safety-related maxii Sensor (Connections 1 - 4)	num values Current loop (Connections ±)	Power supply U _B (DC)
TIF50-S, TIF52-S	without	{-50} -40 +85 °C	-	-	14.5 42 V
TIF50-F, TIF52-F	Flameproof enclosure BVS 10 ATEX E 158 IECEx BVS 10.0103 II 2G Ex db IIC T4/T5/T6 Gb Ex db IIC T4/T5/T6 Gb	-40 +85 °C at T4 -40 +75 °C at T5 -40 +60 °C at T6	-	$U_{M} = 30 \text{ V}$ $P_{M} = 2 \text{ W}$	14.5 30 V
TIF50-F, TIF52-F	Flameproof enclosure TC RU C-DE.BH02.B.00466/20 1 Ex d IIC T6 T4	-60 ²⁾ / -40 +85 °C at T4 -60 ²⁾ / -40 +75 °C at T5 -60 ²⁾ / -40 +60 °C at T6	-	$U_{M} = 30 \text{ V}$ $P_{M} = 2 \text{ W}$	14.5 30 V
TIF50-I, TIF52-I	Intrinsically safe equipment ¹⁾ BVS 16 ATEX E 112 X IECEx BVS 16.0075X		see installation drawing in the operating	see installation drawing in the operating instructions at www.wika.com	14.5 29 V
	II (1)2G Ex ia [ia Ga] IIC T4/T5/T6 Gb II 2G Ex ia IIC T4/T5/T6 Gb	-40 +85 °C at T4 -40 +70 °C at T5 -40 +55 °C at T6	instructions at www.wika.com		
	II (1)2D Ex ia [ia Da] IIIC T135 °C Db II 2D Ex ia IIIC T135 °C Db	-40 +40 °C (P _i = 680 mW) -40 +70 °C (P _i = 650 mW)			
TIF50-I, TIF52-I	Intrinsically safe equipment ¹⁾ TC RU C-DE.AA45.B.00918		see installation drawing in	see installation drawing in	14.5 29 V
	0 Ex ia IIC T4/T5/T6 1 Ex ib [ia] IIC T4/T5/T6	-60 ²⁾ / -40 +85 °C at T4 -60 ²⁾ / -40 +70 °C at T5 -60 ²⁾ / -40 +55 °C at T6	the operating instructions at www.wika.com	the operating instructions at www.wika.com	
	DIP A20 Ta 120 °C DIP A21 Ta 120 °C	-60 $^{2)}$ / -40 +40 $^{\circ}$ C (P _i = 680 mW) -60 $^{2)}$ / -40 +70 $^{\circ}$ C (P _i = 650 mW)			

¹⁾ The installation conditions for the transmitters and displays must be considered for the final application.
2) Special version on request (only available with specific approvals)

Measuring devia	tion, te	emperature coefficient, lo	ng-term stability				
Effect of load		Not measurable					
Power supply effect Not mea		Not measurable	measurable				
Warm-up time After approx. 5 minutes the instrument will function to the specifications			trument will function to the specifications (accuracy)			
Input		ring deviation per I 60770, 23 °C ±3 K	Mean temperature coefficient (TC) for each 10 K change in ambient temperature in the range -40 +85 °C	Lead resistance effects	Long-term stability after 1 year		
■ Resistance thermometer Pt100/JPt100/ Ni100 ¹)	MV > 2	C ≤ MV ≤ 200 °C: ±0.10 K 00 °C: + 0.01 % IMW-200 KI) ²⁾	±(0.06 K + 0.015 % MV)	no effect 0.05 % (0 to 50 Ω each wire) MV, gre	$\pm 60~\text{m}\Omega$ or 0.05 % of MV, greater value applies		
■ Resistance sensor	≤ 2,140 ≤ 4,390	2: $0.053 \Omega^{4}$) or 0.015% MV ⁵) Ω : $0.128 \Omega^{4}$) or 0.015% MV ⁵) Ω : $0.263 \Omega^{4}$) or 0.015% MV ⁵) Ω : $0.503 \Omega^{4}$) or 0.015% MV ⁵)	$\pm (0.01 \Omega + 0.01 \% MV)$	$\pm 0.02~\Omega/10~\Omega$ (0 to 50 Ω each wire) 2-wire: Resistor of the connection lead $^{3)}$			
■ Potentiometer	R _{part} /R _t	otal is max. ±0.5 %	±(0.1 % MV)		$\pm 20~\mu V$ or		
■ Thermocouples Type E, J	±(0.3 K MV > 0	C < MV < 0 °C: + 0.2 % IMVI) °C: + 0.03 % MV)	Type E: MV > -150 °C: ±(0.1 K + 0.015 % IMVI) Type J: MV > -150 °C: ±(0.07 K + 0.02 % IMVI)	$6~\mu V$ / 1,000 Ω $^{6)}$	0.05 % of MV, greater value applies		
Type T, U	±(0.4 K MV > 0	C < MV < 0 °C: + 0.2 % IMVI) °C: + 0.01 % MV)	-150 °C < MV < 0 °C: ±(0.07 K + 0.04 % MV) MV > 0 °C: ±(0.07 K + 0.01 % MV)				
Type R, S	±(1.45 400 °C	MV < 400 °C: K + 0.12 % IMV - 400 KI) < MV < 1,600 °C: K + 0.01 % IMV - 400 KI)	Type R: $50 ^{\circ}\text{C} < \text{MV} < 1,600 ^{\circ}\text{C}$: $\pm (0.3 \text{K} + 0.01 ^{\circ} \text{IMV} - 400 \text{KI})$ Type S: $50 ^{\circ}\text{C} < \text{MV} < 1,600 ^{\circ}\text{C}$: $\pm (0.3 \text{K} + 0.015 ^{\circ} \text{IMV} - 400 \text{KI})$				
Туре В	±(1.7 K	< MV < 1,000 °C: + 0.2 % IMV - 1,000 KI) ,000 °C:	450 °C < MV < 1,000 °C: ±(0.4 K + 0.02 % IMV - 1,000 KI) MV > 1,000 °C: ±(0.4 K + 0.005 % (MV - 1,000 K))				
Туре К	±(0.4 K 0 °C < I	S < MV < 0 °C: + 0.2 % IMVI) MV < 1,300 °C: + 0.04 % MV)	-150 °C < MV < 1,300 °C: ±(0.1 K + 0.02 % IMVI)				
Type L	±(0.3 K	C < MV < 0 °C: + 0.1 % IMVI) °C: ±(0.3 K + 0.03 % MV)	-150 °C < MV < 0 °C: ±(0.07 K + 0.02 % IMVI) MV > 0 °C: ±(0.07 K + 0.015 % MV)				
Type N	±(0.5 K	C < MV < 0 °C: + 0.2 % IMVI) °C: ±(0.5 K + 0.03 % MV)	-150 °C < MV < 0 °C: ±(0.1 K + 0.05 % IMVI) MV > 0 °C: ±(0.1 K + 0.02 % MV)				
■ mV sensor		mV: 10 μV + 0.03 % IMVI mV: 15 μV + 0.07 % IMVI	2 μV + 0.02 % IMVI 100 μV + 0.08 % IMVI				
■ Cold junction ⁷⁾	±0.8 K		±0.1 K		±0.2 K		

Total measuring deviation

Output

Addition: Input + output per DIN EN 60770, 23 °C ± 3 K

MV = measured value (temperature measured values in $^{\circ}C)$ Measuring span = configured end of measuring range - configured start of measuring range

±0.03 % of measuring span

- 1) For sensor Ptx (x = 10 ... 1,000) applies: for $x \ge 100$: Permissible error, as for Pt100 for x < 100: Permissible error, as for Pt100 with a factor (100/x)
- 2) Additional error for resistance thermometers in a 3-wire configuration with zero-balanced cable: 0.05 K
- The specified resistance value of the sensor wire can be subtracted from the calculated sensor resistance.
 Dual sensor: Configurable for each sensor separately
- Double value at 3-wire
- 5) Greater value applies

±0.03 % of measuring span

- 6) Within a range of 0 ... 10 $k\Omega$ lead resistance
- 7) Only for thermocouple

Basic configuration:

Input signal: Pt100 in 3-wire connection, measuring range: 0 ... 150 °C

±0.05 % of span

Example calculation

Pt100 / 4-wire / measuring range 0 150 °C / ambient temperature 33 °C	/
Input Pt100, MV < 200 °C	±0.100 K
Output ±(0.03 % of 150 K)	±0.045 K
TC 10 K - input ±(0.06 K + 0.015 % of 150 K)	±0.083 K
TC 10 K - output ±(0.03 % of 150 K)	±0.045 K
Measuring deviation (typical) √input² + output² + TC _{input} ² + TC _{output} ²	±0.145 K
Measuring deviation (maximum) (input + output + TC _{input} + TC _{output})	±0.273 K

Thermocouple type K / measuring range 0 400 °C / internal compensation (cold junction) / ambient temperature 23 °C			
Input type K, 0 °C < MV < 1,300 °C $\pm (0.4 \text{ K} + 0.04 \% \text{ of } 400 \text{ K})$	±0.56 K		
Cold junction ±0.8 K	±0.80 K		
Output ±(0.03 % of 400 K)	±0.12 K		
Measuring deviation (typical) $\sqrt{\text{input}^2 + \text{cold junction}^2 + \text{output}^2}$	±0.98 K		
Measuring deviation (maximum) (input + cold junction + output)	±1.48 K		

Monitoring	
Test current for sensor monitoring 1)	Nom. 20 μA during test cycle, otherwise 0 μA
Monitoring NAMUR NE89 (monitoring of input lea	ad resistance)
■ Resistance thermometer (Pt100, 4-wire)	R_{L1} + R_{L4} > 100 Ω with hysteresis 5 Ω R_{L2} + R_{L3} > 100 Ω with hysteresis 5 Ω
■ Thermocouple	$R_{L1} + R_{L4} + R_{thermocouple} > 10~k\Omega$ with hysteresis 100 Ω
Sensor break monitoring	Always active
Self-monitoring	Active permanently, e.g. RAM/ROM test, logical program operating checks and validity check
Measuring range monitoring	Monitoring of the set measuring range for upper/lower deviations Standard: Deactivated
Monitoring of input lead resistance (3-wire)	Monitoring of the resistance difference between lead 3 and 4; an error will be indicated if there is a difference of $> 0.5~\Omega$ between leads 3 and 4

¹⁾ Only for thermocouple

Field case		
Material	Aluminium, window from polycarbonaStainless steel, window from polycarb	
Colour	Aluminium: Night blue, RAL 5022	Stainless steel: Silver
Cable bushings	3 x M20 x 1.5 or 3 x ½ NPT	
Ingress protection	IP66	
Weight	Aluminium: approx. 1.5 kg	Stainless steel: approx. 3.7 kg
Dimensions	See drawing	

Ambient conditions	
Ambient temperature	-60 ¹⁾ / -40 +85 °C
Functional area of the display	-20 ²⁾ +70 °C
Climate class per IEC 654-1: 1993	Cx (-20 +85 °C, 35 85 % r. h., non-condensing)
Maximum permissible humidity	93 % r. h. ±3 %
Vibration resistance per IEC 60068-2-6:2007	3 g
Shock resistance per IEC 68-2-27: 1987	30 g
Electromagnetic compatibility (EMC)	EN 61326 emission (group 1, class B) and interference immunity (industrial application), and also NAMUR NE21

¹⁾ Special version on request (only available with specific approvals)

Communication HART® protocol rev. 5 including burst mode and multidrop

Interoperability (i.e. compatibility between components from different manufacturers) is a strict requirement of HART® instruments. The field transmitter is compatible with almost every open software and hardware tool; among other things with:

- 1. User-friendly WIKA configuration software, free-of-charge download via www.wika.com
- 2. HART® communicator FC375, FC475, MFC4150, MFC5150, Trex: T32 device description integrated
- 3. Asset Management Systems
 - 3.1 AMS: T32_DD completely integrated and upgradable with old versions
 - 3.2 Simatic PDM: T32_EDD completely integrated from version 5.1, upgradable with version 5.0.2
 - 3.3 Smart Vision: DTM upgradable per FDT standard from SV version 4
 - 3.4 PACTware: DTM completely integrated and upgradable as well as all supporting applications with FDT interface
 - 3.5 Field Mate: DTM upgradable

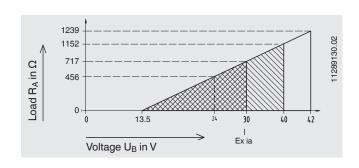
Attention:

For direct communication via the serial interface of a PC/notebook, a HART® modem is needed (see "Accessories"). As a general rule, parameters which are defined in the scope of the universal HART® commands (e.g. the measuring range) can, in principle, be edited with all HART® configuration tools.

Load diagram

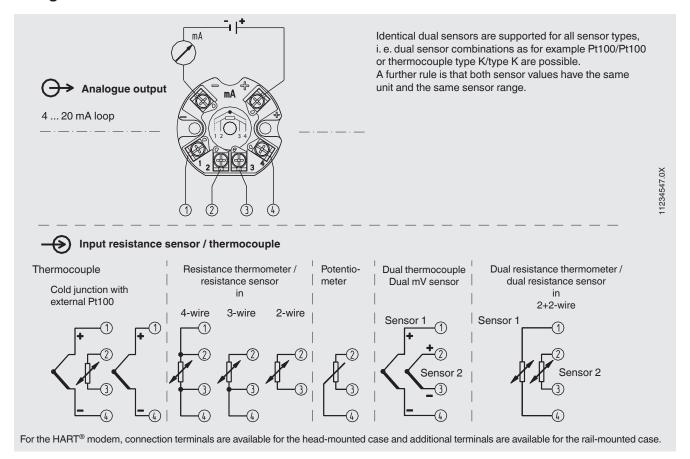
The permissible load depends on the loop supply voltage.

Load $R_A \le (UB - 13.5 \text{ V}) / 0.023 \text{ A with } R_A \text{ in } \Omega \text{ and } U_B \text{ in V}$ (without HART®)

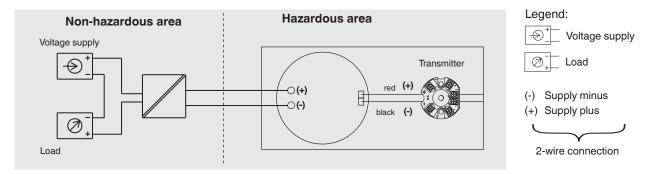


²⁾ In previous ambient temperatures < -20 °C a delayed recovery of the indication function could be expected, especially in case of low loop current.

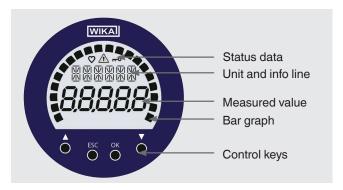
Designation of connection terminals



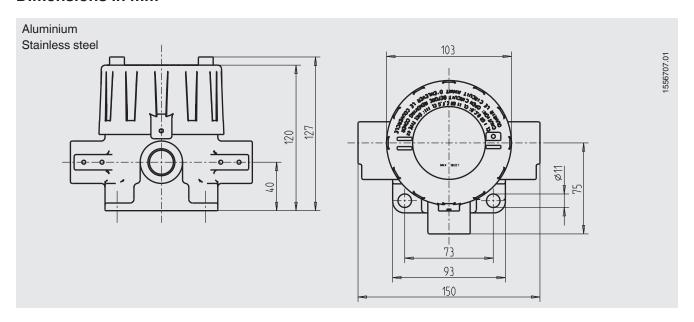
Electrical connection



User interface



Dimensions in mm



Accessories

Model	Description	Order number		
Programming unit, model PU-H				
VIATOR® HART® USB	HART® modem for USB interface	11025166		
VIATOR® HART® USB PowerXpress™	HART® modem for USB interface	14133234		
VIATOR® HART® RS-232	HART® modem for RS-232 interface	7957522		
VIATOR® HART® Bluetooth® Ex	HART® modem for Bluetooth interface, Ex	11364254		
Magnetic quick connector magWIK	 Replacement for crocodile clips and HART® terminals Fast, safe and tight electrical connection For all configuration and calibration processes 	14026893		

Approvals

Logo	Description	Region
CE	EU declaration of conformity	European Union
	EMC directive EN 61326 emission (group 1, class B) and interference immunity (industrial application)	
	RoHS directive	

Optional approvals

Logo	Description	Region
€x>	EU declaration of conformity	European Union
	ATEX directive Hazardous areas	
IEC IECEX	IECEx Hazardous areas	International
EHLEx	EAC	Eurasian Economic Community
	EMC directive	
	Hazardous areas 1)	
©	PAC Russia Metrology, measurement technology	Russia
B	PAC Kazakhstan Metrology, measurement technology	Kazakhstan
-	MChS Permission for commissioning	Kazakhstan
(PAC Belarus Metrology, measurement technology	Belarus
•	PAC Ukraine Metrology, measurement technology	Ukraine
	DNOP - MakNII	Ukraine
	Mining	
	Hazardous areas	
-	PESO Hazardous areas	India

¹⁾ The installation conditions for the transmitters must be considered for the final application.

Manufacturer's information and certifications

Logo	Description
-	China RoHS directive

Certificates (option)

Certificates	
Certificates	2.2 test report3.1 inspection certificate
Calibration	■ DAkkS calibration certificate

[→] Approvals and certificates, see website

Ordering information

Model / Explosion protection / Case material / Transmitter / Cable bushings / Threaded connection for cable bushing / Certificates / Options

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